We learned…

* Different libraries are available for image processing
* How to use a library called “picamera” for image processing
* Motion vectors are capable to detect motion in sequences of images
* How balance wheels and watches are working
* Light intensity influences the measurements
* The selected image section influences the measurements
* The camera parameters influence the measurements
* How to calculate the frequency based on the motion vectors

We want to learn…

* What’s the maximum accuracy we can achieve with our tools
* Where are the errors
* How long we have to measure to achieve the maximum accuracy
* If there are possibilities to improve our accuracy through extrapolation or other things